



Analyse Best Practice Parameter Setting to Effectively Programme Robots To Meet Manufacturing Specifications

29th-30th November, Birmingham, UK

LEADING
INNOVATIONS



WWW.PROFACTOR.AT

Topics to be addressed

- From EU funded research to Industrial Application
- Robotic Co-worker Technologies development for industrial applications
- Workflow-based robot process design and execution
- Onboard process planning and configuration tools
- **Symbiotic** human-robot collaboration for multimodal Human Robot Interaction

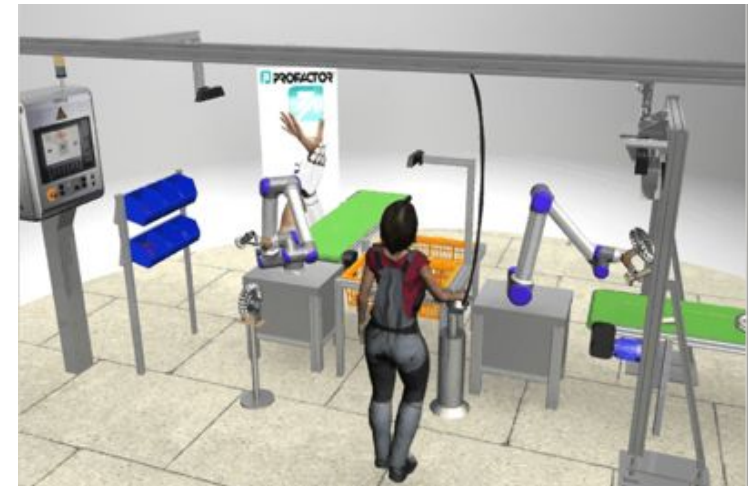
PROFACTOR Profil

- Austria's no. 1 in **applied production research**
- Multidisciplinary team with **74 employees**
- Business locations in **Steyr** and **Vienna**
- **6 Mio. EUR turn-over** (2015)
- Since 1995 **over 1,700 (inter-)national projects** in industry (**1,360**) und research (**350**)



Research Area- Industrial Assistive Systems

- Increasing the competitiveness!
- Aim: to support human beings in a in a volatile, richly varied and highly flexible production
 - Decision-making competence, knowledge and experience of workers
 - Precision, endurance, speed or the power of the machine
- Intelligent Automatization for Mass Customization.



Ergonomic Collaboration Human & Machine (LOCOBOT)

➤ Initial situation

- Reduction of “red” work places

➤ Research approach

- Solutions for practical division of work between human and machine, which is realizable with adequate use of resources

➤ Results

- **Improvement of ergonomics through development of assistant systems**
- Modular design of **intelligent hard- and software components** (e.g. compliant robot arm)
- Software environment for **user-friendly development of solutions and coordination** of component interaction



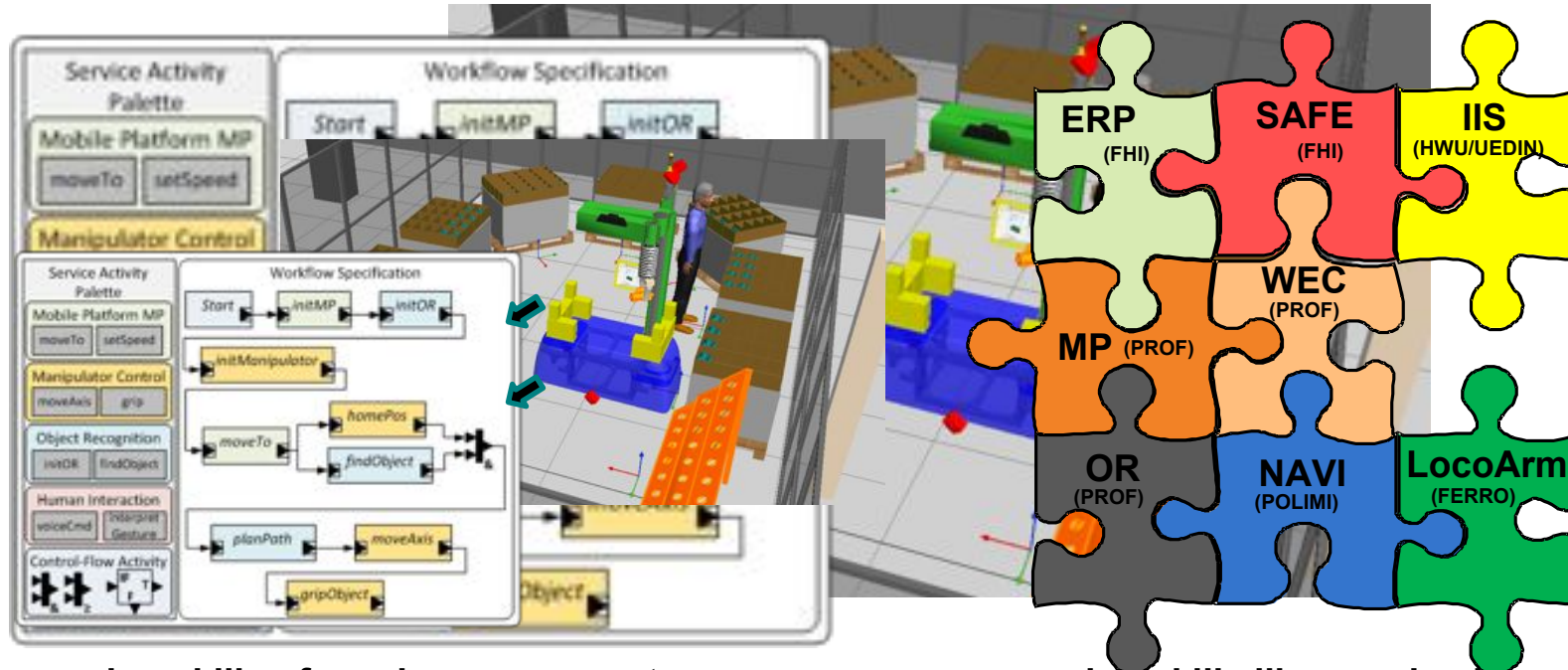
Locobot's application development

Modeling application logic

- user-friendly workflow modeling environment (WME)

Supervisory control is generated

- **‘workflow execution control’ (WEC)**



using skills of service components

= using skills like puzzle pieces for the application logic

Results – EuroNews Report



„A robot for every work shop“

Fast Setup

Easy to use

Fast programming



Versatile

Small lotsizes

Ad-hoc usage

Challenges for flexible robotic systems

- Reduction of Invest
- Cover a wide area of use
- Shortest ramp up periods for on-demand applications
- Lower training, operating- and maintenance costs



A robot for each working place (each garage) - features

- Movable, modulare Systems
- Short Ramp up (few hours)
- Modification in a few minutes
- Process execution also by Non Experts using only one Interface (HMI)
- Communication / Data Input using an intuitive HMI System with automatic functions
- Adaptive process execution

Solution– Software/Hardware construction kit

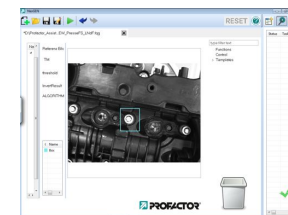
➤ Sensors & Tools



➤ Robots (UR, KUKA, nn)



➤ Control system (IPC, PC) + Software



XRob – Features

- **Workflow – based**, intuitive und integrated **process mapping** and **execution in only one user Interface**
- **Consolidation of existing Input tools of the sub components** (Robot, Vision, Tool, usw...)
- **Intelligent, semi automatic tools** for process planning
- **Use of standardized IT Interfaces** (TCP/IP, DIO, ProfiNet,...) – fast integration to the Enviroment

XRob – Software Tool Kit



Workflow -Manager

Robotcontrol

Tooling control

Safety control

Interfaces

2D/3D-position detection

Processsimulation

Automatic path planning

3D-Workspace scanning

HMI-System

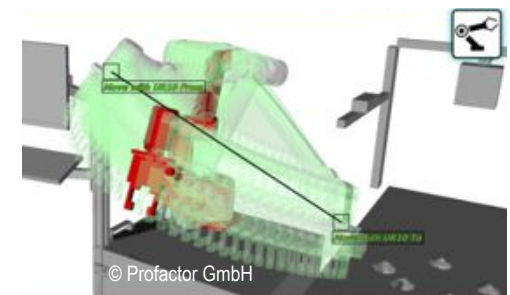
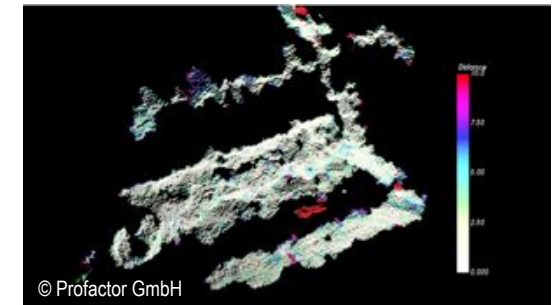
Cognitive Function

Online - Tacking

XRob – Technologies

Tool kit for quick setup and safe operation

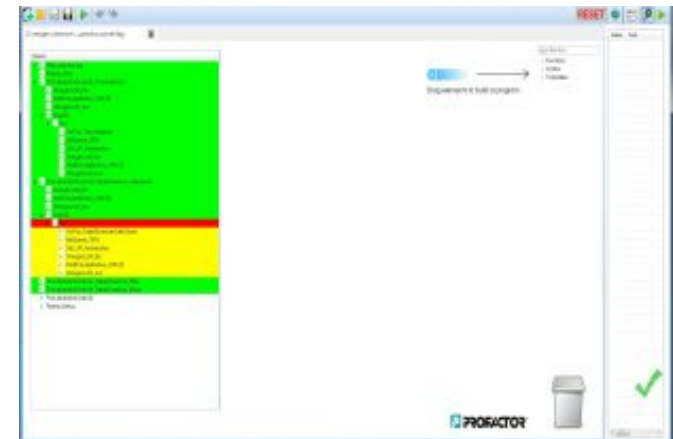
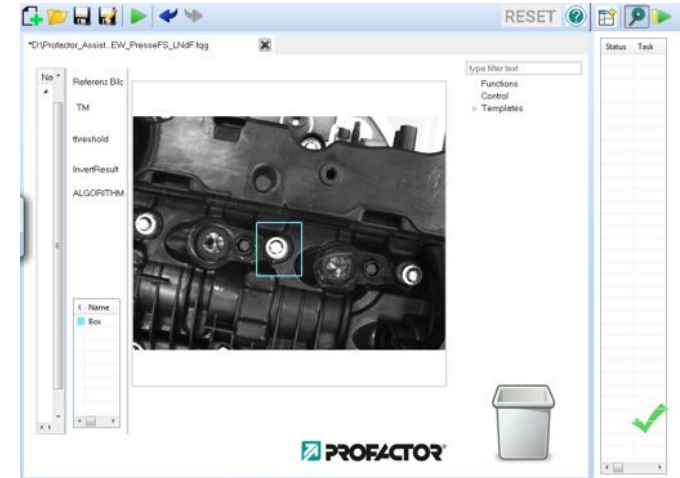
- 3D scanning of the workspace
- Semi automatic creating of a collision model
- Inline - 2D/3D position detection
- Collision avoidance through automatic path planning



XRob – Technologies

Tool kit for quick setup and safe operation

- Configuration all involved components via a user interface
- Workflow-based process
- Process status and progress mapping



XRob

The Software system X Rob allows the creation of complex robot application within a few minutes

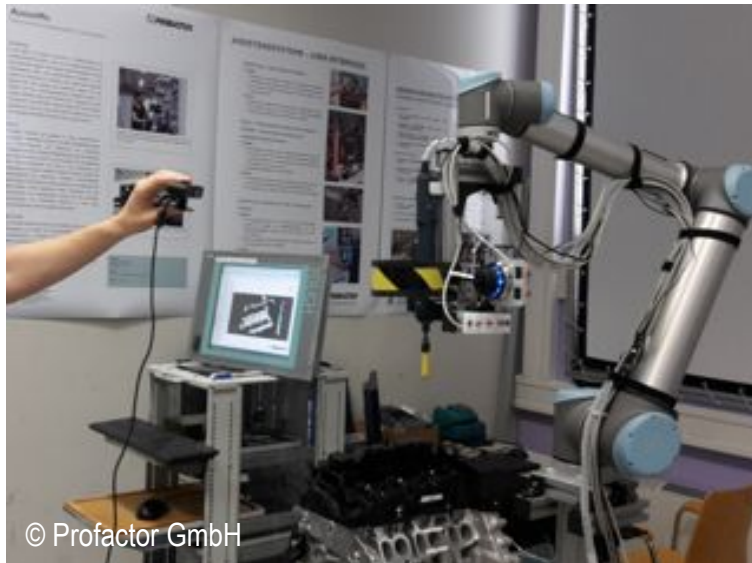


XRob – Applications



Screwing Assistant

- Screwing of covers and mouting parts on mobile workpiece holder in the assembly line



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R&D Project AssitMe BMW Steyr 2015



© Profactor GmbH

Pilotsytem Flexible Screwing Station BRP Rotax 2016



XRob – Anwendungen

Screwing Assistant

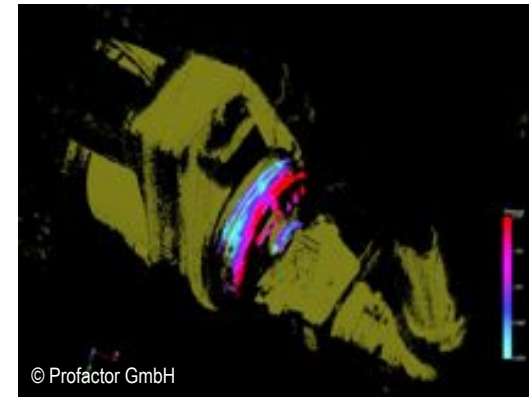
➤ Screwing of accessories / Covers



XRob – Application

Inspection Assitant – Flexible Quality Gate

- 3D-Inspection of des locking conditions of plugs and oil cover plates (since autuum 2013)



IO / NIO Auswertung der 3D-Daten



XRob – Applications

Inspection Assistant

- 3D Inspection of Plugs and Oil cap on the engine
- Acoustic Testing System for vehicel body parts



MÜLLER-BBM
VibroAkustik Systeme



Audi



© Profactor GmbH

Pilotproject Flexible Quality Gate BMW Steyr 2013



Flexible Acoustic Inspection Systems 2015



XRob – Anwendungen

Assembly Assistant

➔ 3rd Hand Support



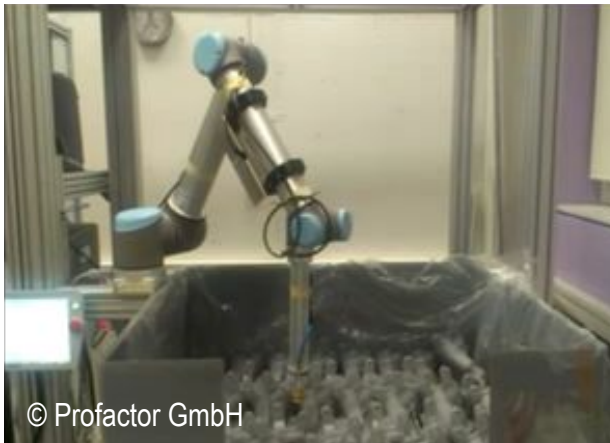
R&D-Project 3rd-Hand Support 2016



XRob – Application

Handling Assistant

➤ Pin Picking (since 2009)



New: Selective Handling (AR-based)



XRob – Application

Paint Assistant

➤ Painting of 3D-Objects

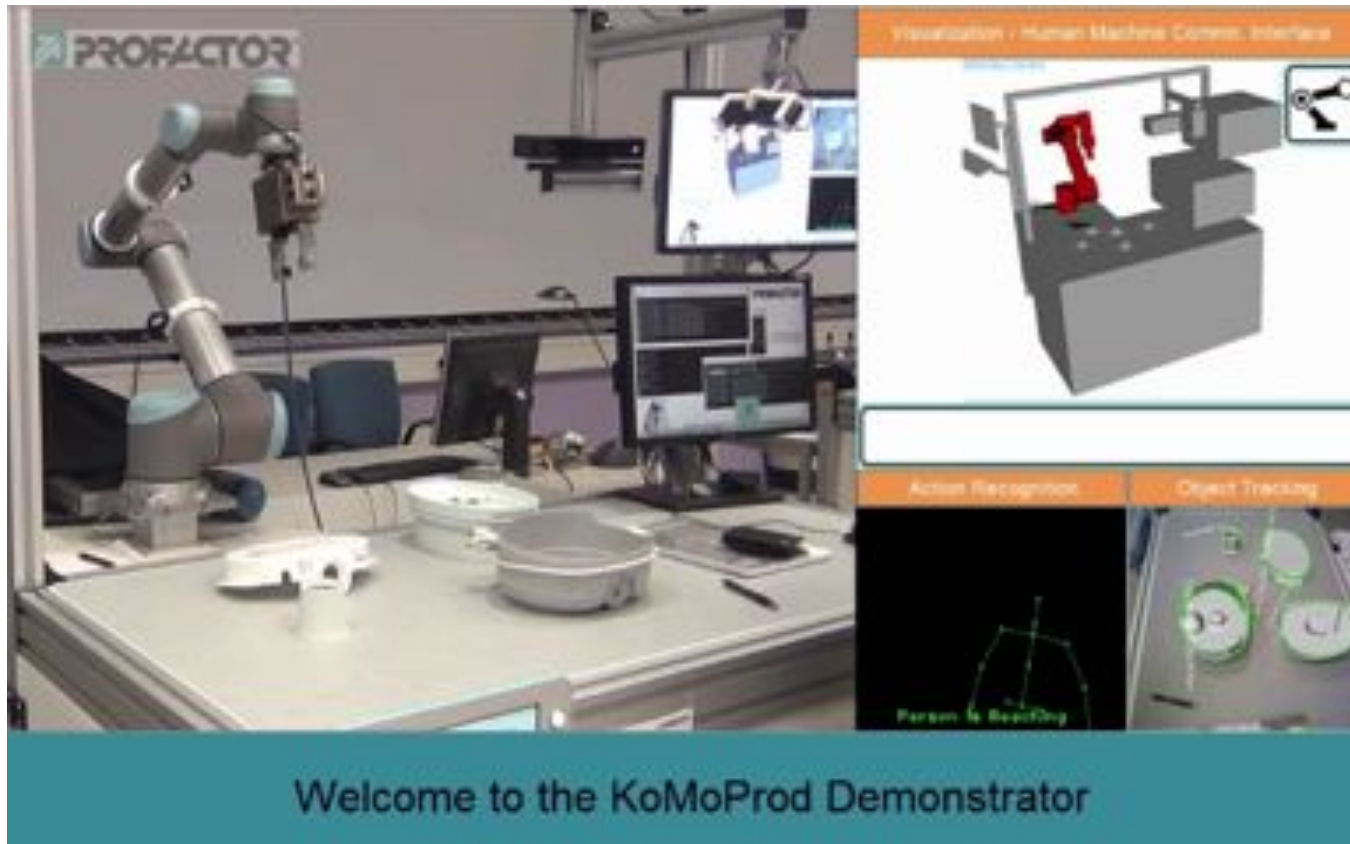


Printing on 3D Surfaces



Research projects

- Cognitive interaction- robot knows user requirements



SYMBIOTIC

 **PROFACTOR®**



Symbiotic human-robot collaboration for safe and dynamic multimodal manufacturing systems (SYMBIOTIC)

Early results and outlook for human robot symbiosis

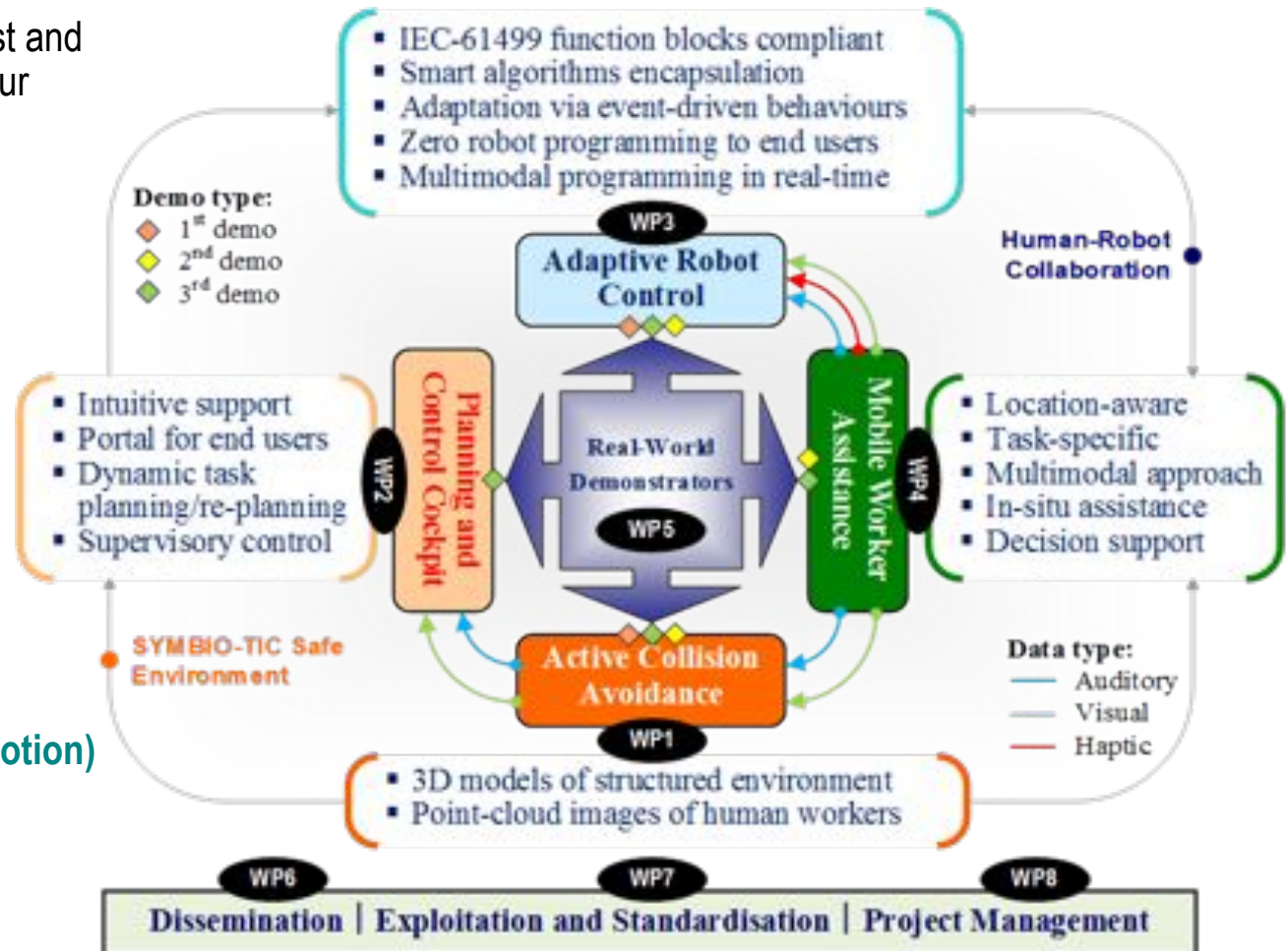
Project Overview

- The project's final goal is to test and quantify the aforementioned four objectives in terms of:

- Safety
- Feasibility
- Intuitiveness
- Adaptability
- Scalability

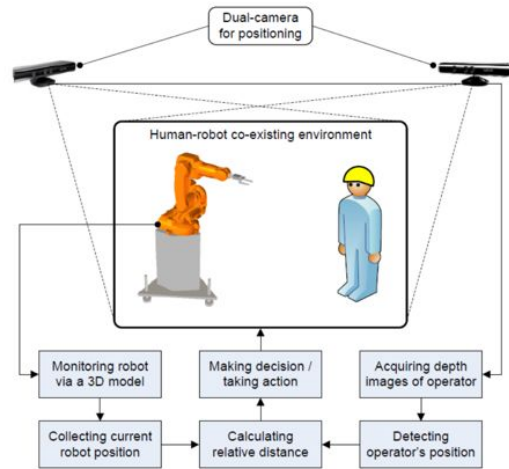
- Three demonstrators:

- Food-processing (Robomotion)
- Aeronautics (Aciturri)
- Automotive (Volvo Cars)

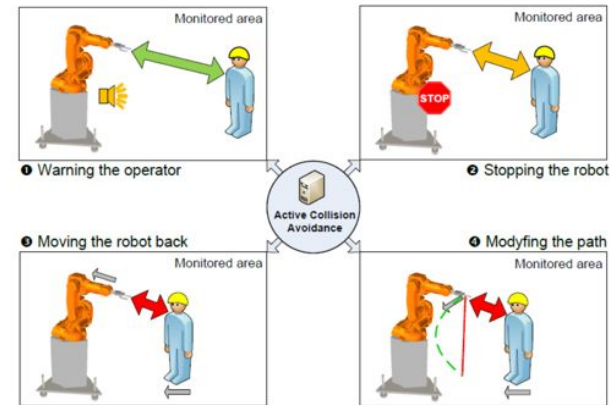


Project Objectives

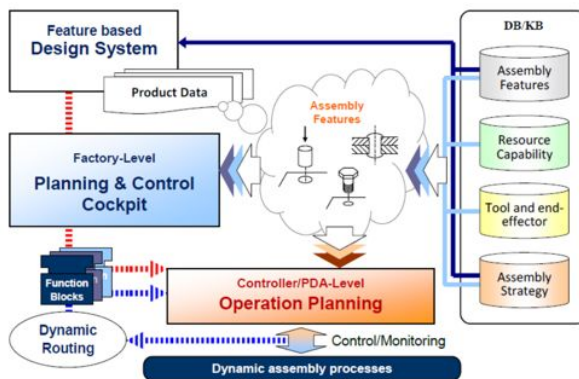
Active collision avoidance for safe human robot collaboration in real time.



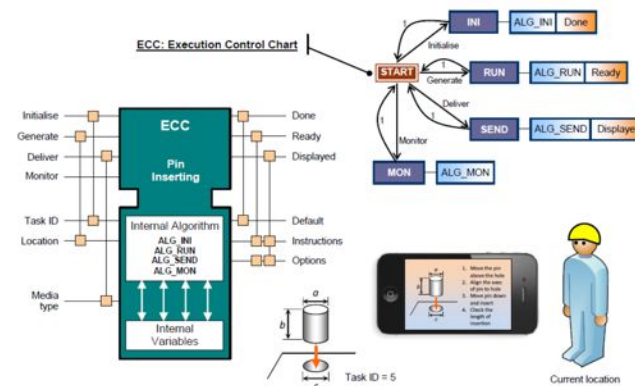
Adaptive task plan generation for robots and human workers allowing collaboration.



Dynamic adaptation to changes in the shop-floor environment with zero programming for the robot users.



Instructions generation for supporting human workers on what and how to do.





Thank You !

Contact

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Visit X - Rob on HMI In Hannover

Hall 2, Booth A44 - 24.-28. April, Hannover